

## CLAIMS:

1. A program storage device, readably by a machine, tangibly embodying programming instructions to perform method steps for constructing a call graph, the programming instructions comprising:

5 determining for each method  $M$ , a set of types  $S_M$  of objects that may occur in method  $M$ ;

determining for each field  $F$ , a set of types  $S_F$  of objects that may be stored in field  $F$ ;

10 determining the allocation sites inside the body of method  $M$ ;

determining the set of directly called methods  $M'$  inside the body of method  $M$ ;

and

determining the set of virtually called methods  $M''$  inside the body of method  $M$ .

15 2. The program storage device according to claim 1, further comprising the programming instructions of:

adding  $T$  to  $S_M$  for each allocation of type  $T$  that occurs in method  $M$ .

3. The program storage device according to claim 2, further comprising the programming instructions of:

20 for each direct call to method  $M'$  in a body of method  $M$  performing the steps of:

adding any type that occurs in  $S_M$  and that is a subtype of the type of a parameter of  $M'$  to  $S_{M'}$ ; and

adding any type that occurs in  $S_{M'}$  and that is a subtype of the

25 return type of  $M'$  to  $S_M$ .

4. The program storage device according to claim 3, further comprising the programming instructions of:

for each virtual call to method  $M'$  in the body of method  $M$ :

- 5 using  $S_M$ , determine each method  $M''$  that may be reached by the dynamic dispatch:  
adding any type that occurs in  $S_M$  and that is a subtype of the type of a parameter of  $M''$  to set  $S_{M''}$ ;  
adding any type that occurs in  $S_M$  and that is a subtype of the  
10 return type of  $M''$  to  $S_M$ .

5. The program storage device according to claim 4, further the programming instructions of:

for each field  $F$  read by method  $M$ , add any type that occurs in  $S_F$  to  $S_M$ ; and

5 for each field  $F$  with type  $T$  written by method  $M$ , add any type that occurs in  $S_M$  and that is a subtype of  $T$  to  $S_F$ .

6. The program storage device according to claim 1, further comprising the programming instructions of:

20 using the call graph computed above in a compiler as a basis for performing optimizations such as inlining.

7. The program storage device according to claim 1, further comprising the programming instructions of:

25 using the call graph computed above in a reporting tool to report call graph information to a user.

8. A program storage device, readably by a machine, tangibly embodying instructions to perform method steps for constructing a call graph, the method comprising:

5 determining for each method  $M$ , only one set of types  $S_M$  of objects that may occur in method  $M$ ; and

determining for each field  $F$ , only one set of types  $S_F$  of objects that may be stored in field  $F$ ; and

determining the allocation sites inside the body of method  $M$ ;

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9. The program storage device according to claim 8, further comprising the steps of:  
determining the set of directly called methods  $M'$  inside the body of method  $M$ ;

and

15 determining the set of virtually called methods  $M''$  inside the body of method  $M$ .

10. A method for constructing a call graph, the method comprising:  
determining for each method  $M$ , a set of types  $S_M$  of objects that may occur in method  $M$ ;  
determining for each field  $F$ , a set of types  $S_F$  of objects that may be stored in field  $F$ ;  
determining the allocation sites inside the body of method  $M$ ;  
determining the set of directly called methods  $M'$  inside the body of method  $M$ ;  
and  
determining the set of virtually called methods  $M''$  inside the body of method  $M$ .
11. The method according to claim 10, further comprising:  
adding  $T$  to  $S_M$  for each allocation of type  $T$  that occurs in method  $M$ .
12. The method according to claim 11, further comprising:  
for each direct call to method  $M'$  in a body of method  $M$  performing the steps of:  
adding any type that occurs in  $S_M$  and that is a subtype of the type of a parameter of  $M'$  to set  $S_{M'}$ ; and  
adding any type that occurs in  $S_{M'}$  and that is a subtype of the return type of  $M'$  to set  $S_M$ .

13. The method according to claim 12, further comprising:  
 for each virtual call to method M' in the body of method M:  
     using set  $S_M$ , determine each method M'' that may be reached by  
 5      the dynamic dispatch:  
         adding any type that occurs in  $S_M$  and that is a subtype of the type  
         of a parameter of M'' to set  $S_{M''}$ ;  
         adding any type that occurs in  $S_{M''}$  and that is a subtype of the  
         return type of M'' to set  $S_M$ .
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14. The method according to claim 13, further comprising:  
 for each field F read by method M, add any type that occurs in  $S_F$  to  $S_M$ ; and  
 for each field F with type T written by method M, add any type that occurs in  $S_M$   
 and that is a subtype of T to set  $S_F$ .
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15. The method according to claim 10, further comprising the step of:  
 using the call graph computed above in a compiler as a basis for performing  
 optimizations such as inlining.
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16. The method according to claim 10, further comprising the step of:  
 using the call graph computed above in a reporting tool to report call graph  
 information to a user.

17. A method for constructing a scalable call graph, the method comprising:  
determining for each method M, only one set of types  $S_M$  of objects that may occur in method M; and
- 5 determining for each field F, only one set of types  $S_F$  of objects that may be stored in field F; and  
determining the allocation sites inside the body of method M;
18. The method to claim 17, further comprising the steps of:
- 10 determining the set of directly called methods M' inside the body of method M;  
and  
determining the set of virtually called methods M'' inside the body of method M.

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